



13th ITS EUROPEAN CONGRESS

FULFILLING ITS PROMISES

Brainport Eindhoven, the Netherlands | 3-6 June 2019

Evluon Congress Center
Helmond Automotive Campus

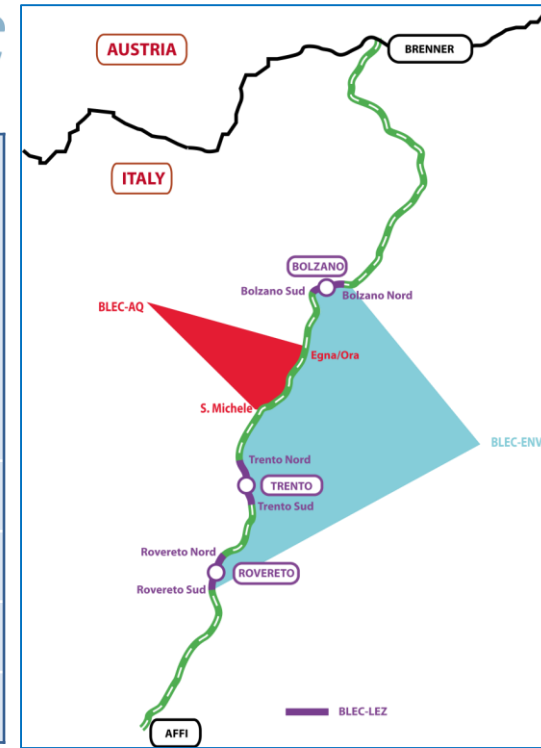


ITS-TP-1846

“About the combination of advanced logics for dynamic VSL activation: an integrated tool to improve traffic flows, control emissions and reduce air pollution”

Roberto Cavaliere, NOI Techpark

The LIFE “BrennerLEC” project

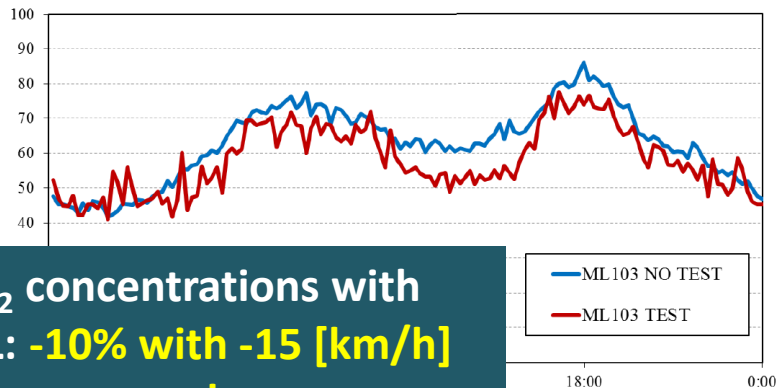


Partners	A22 (coordinator) APPA - Provincia Autonoma di Bolzano APPA - Provincia Autonoma di Trento Università degli Studi di Trento CISMA NOI Techpark (formerly IDM Südtirol / Alto Adige)
Duration	01.09.2016 – 30.04.2021
Overall budget	€ 4.018.005
Eligible budget	€ 3.311.365
LIFE co-financing	€ 1.922.772 (approx. 60% of the eligible budget)

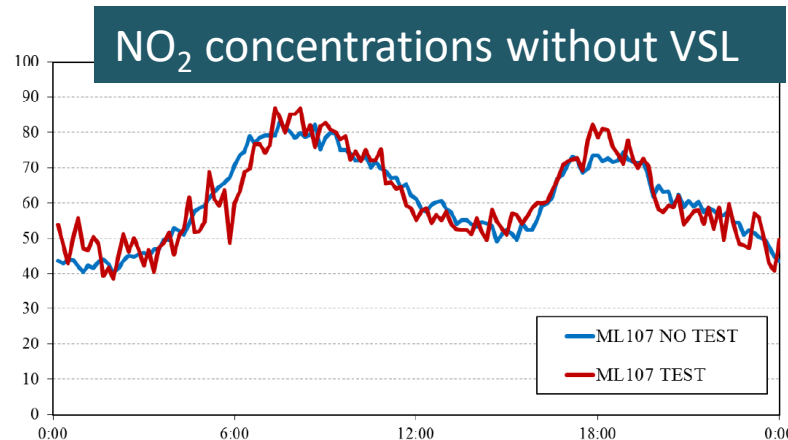
Main objective: develop and demonstrate a «**Low Emissions Corridor**» concept to be applied on the **A22 highway** by means of an **integrated set of traffic control measures** to be activated on the basis of a **proactive logic**.

For more information about the project and first empirical results please refer to BrennerLEC papers at 12th ITS EU Congress 2017 and 25th ITS World Congress 2018.

First empirical assessment about correlation between traffic, air quality and atmospheric stability



NO₂ concentrations with VSL: -10% with -15 [km/h] average speed



NO₂ concentrations without VSL

NO₂ differences between two monitoring sites [µg/m³]

Nr. of light vehicles on both carriageways [vehicles / hour]

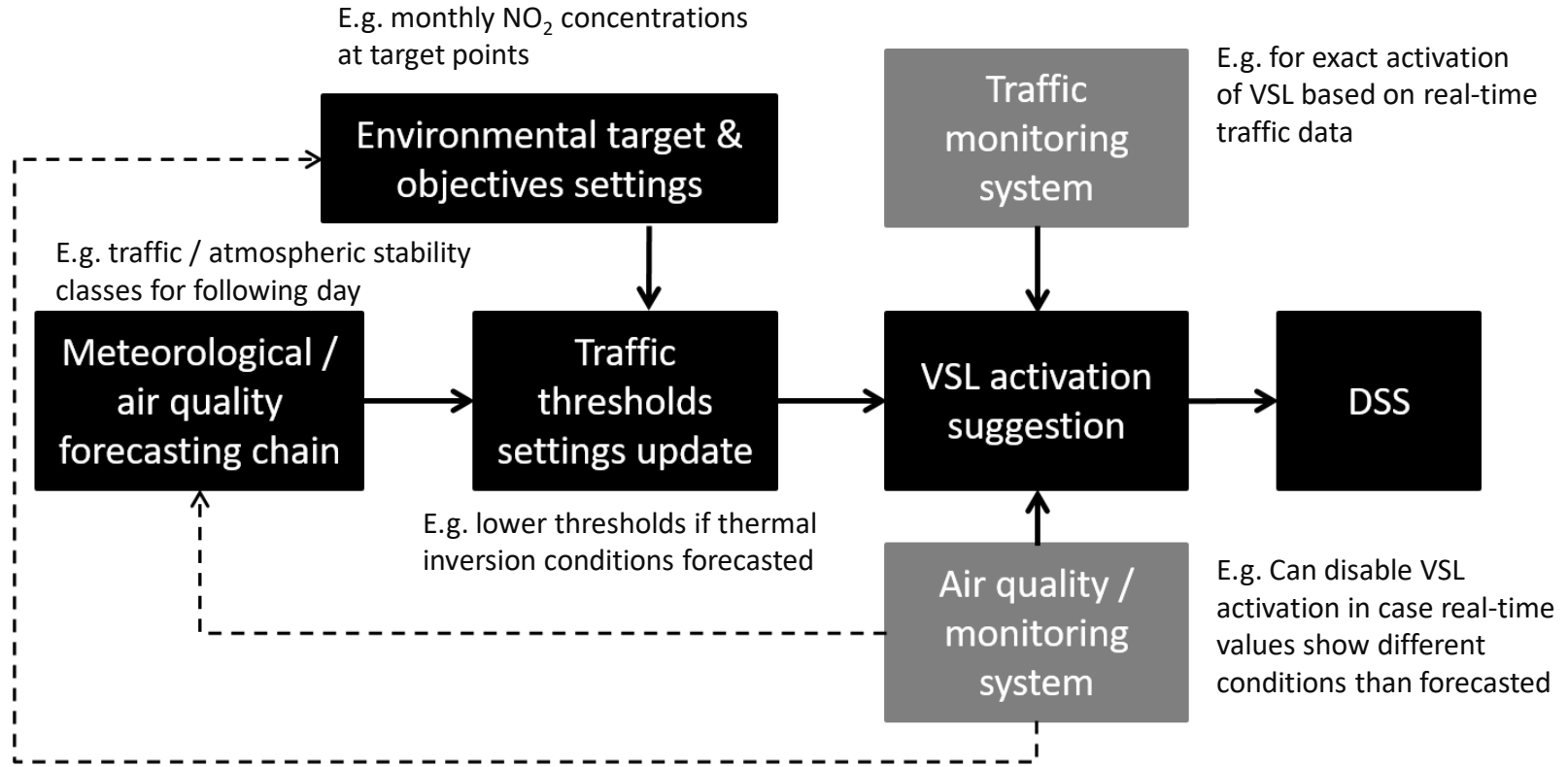
Vertical air temperature gradient 0 – 50 meters [°C / km]

Class	$\Gamma \geq 5$	$-5 \leq \Gamma < 5$	$\Gamma < -5$
$N < 500$	-	1.1	4.5
$500 \leq N < 1.000$	-	2.5	11.2
$1.000 \leq N < 1.500$	1.5	11.4	21.3
$1.500 \leq N < 2.000$	10.5	13.2	26.5
$2.000 \leq N < 2.500$	18.6	18.9	-
$2.500 \leq N < 3.000$	13.9	9.0	-
$N \geq 3.000$	7.7	10.6	-

Most of the benefits with thermal inversion conditions ($\Gamma < -5$) and intense (but not saturated!) traffic conditions

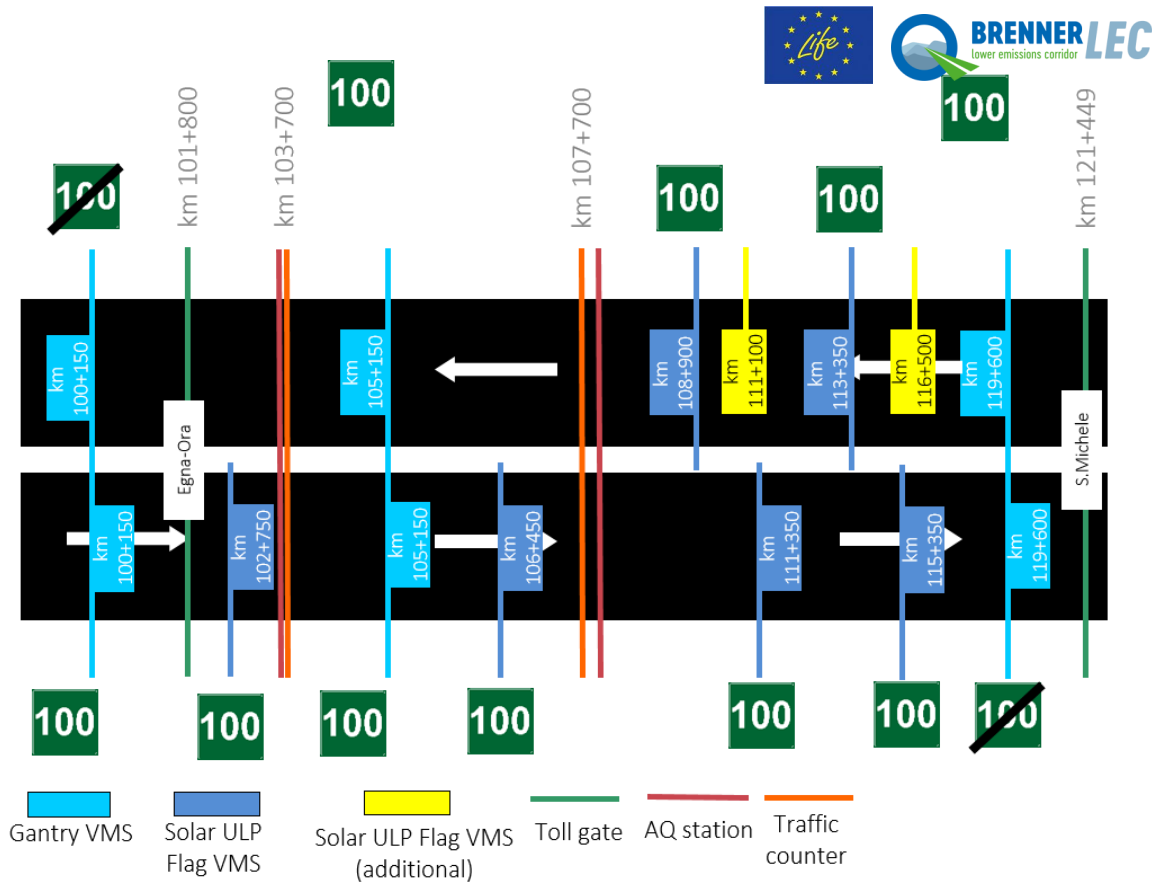
Estimation: 75% of the environmental benefit with 45% of the time in which VSL were active

Logic for dynamic VSL activation triggered by air quality conditions

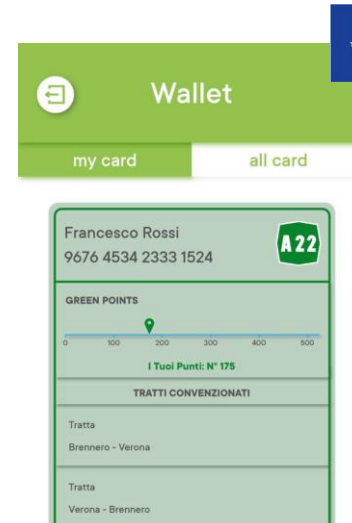
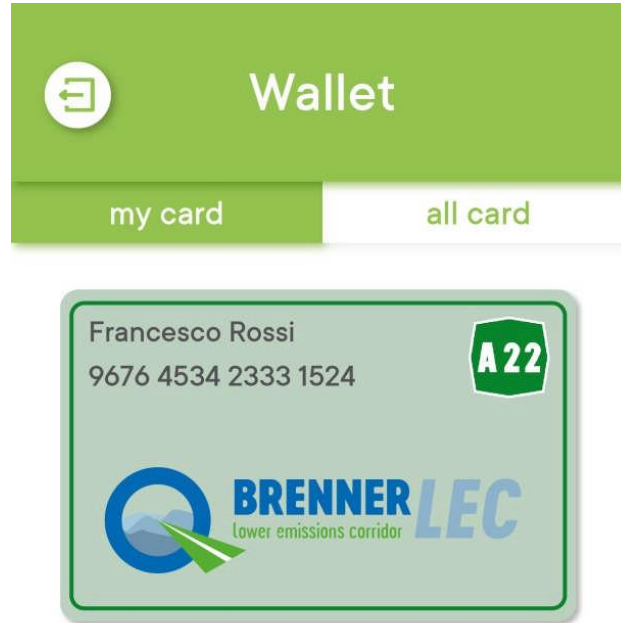


Next testing phase

- Test start scheduled in **06/07-2019**
- **Additional solar flag VMS** to increase the level of information for users
- Also in «**recommended speed**» mode (in particular with low traffic volumes)



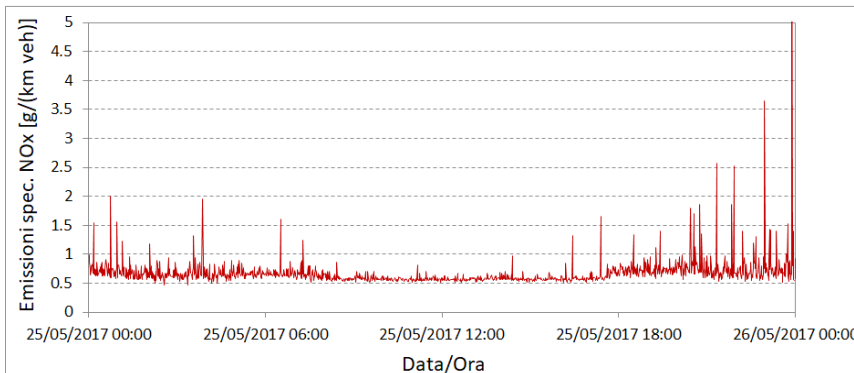
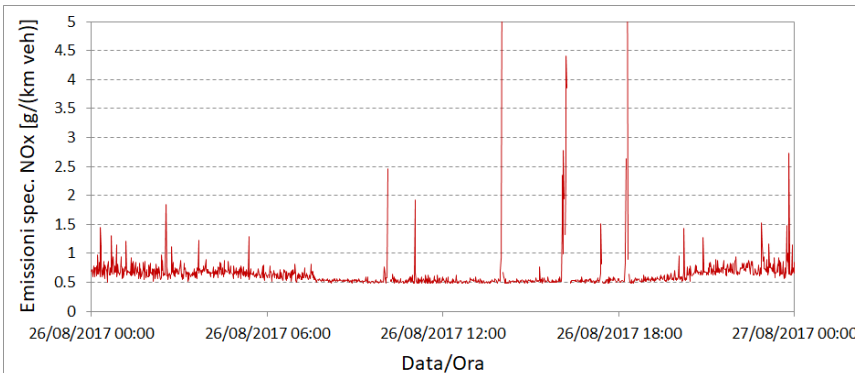
Next testing phase



- An **audio-guide gamification app** to motivate people to comply with VSL, based on detailed **GPS tracking** within the test route.
- **Bigger and smaller rewards** (e.g. fuel discounts, e-bikes, etc.) for commuters and occasional users.

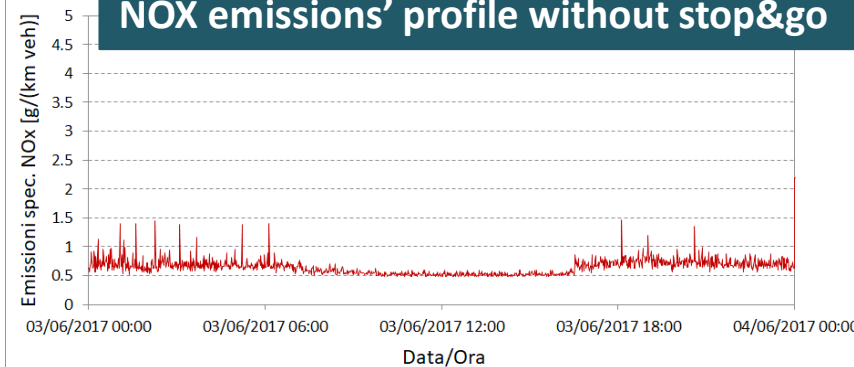
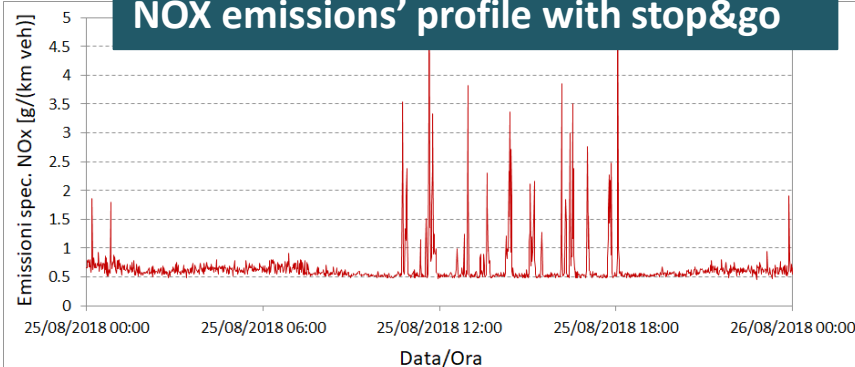


First empirical assessment about emissions' reduction potential associated to stop&go situations (examples)



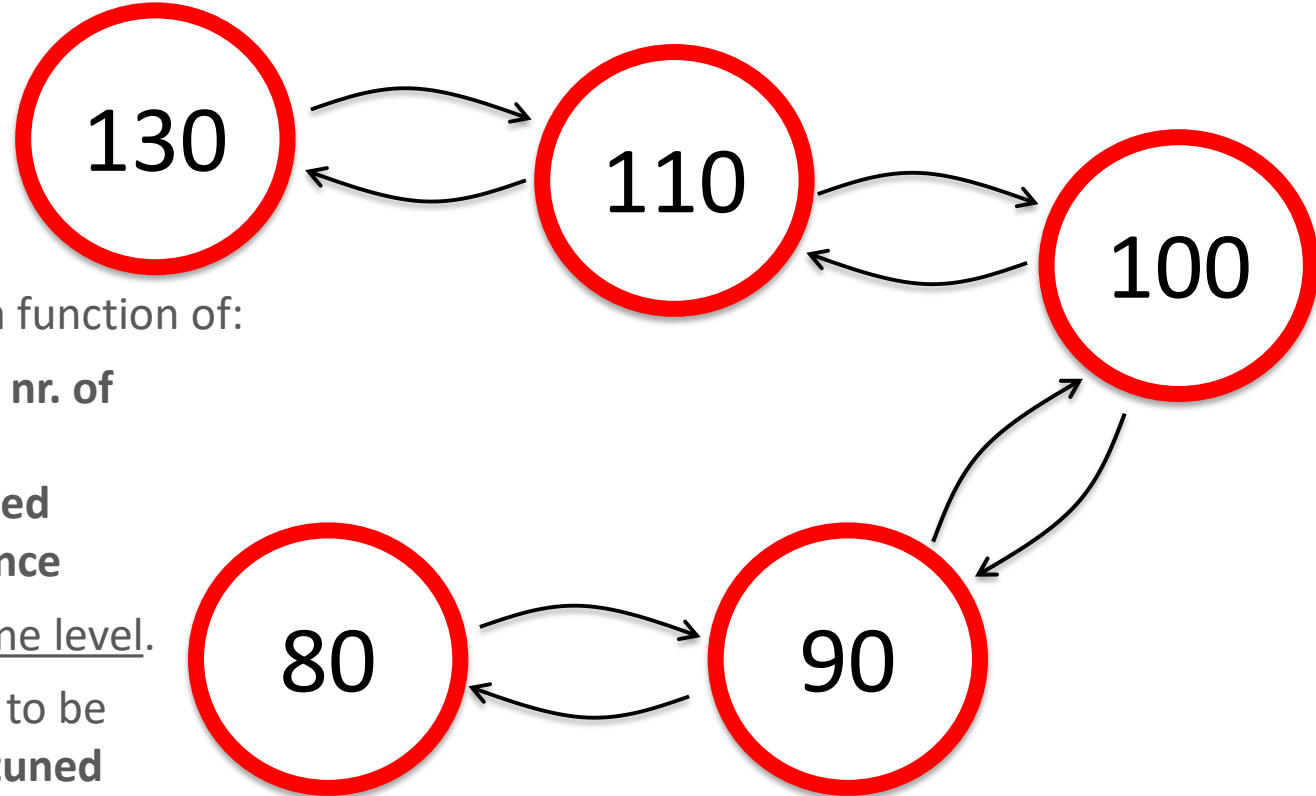
NOx emissions' profile with stop&go

NOx emissions' profile without stop&go



Comparison: +33% [g NO_x /km·veh], +17% [g CO₂ /km·veh]

Logic for dynamic VSL activation triggered by traffic conditions



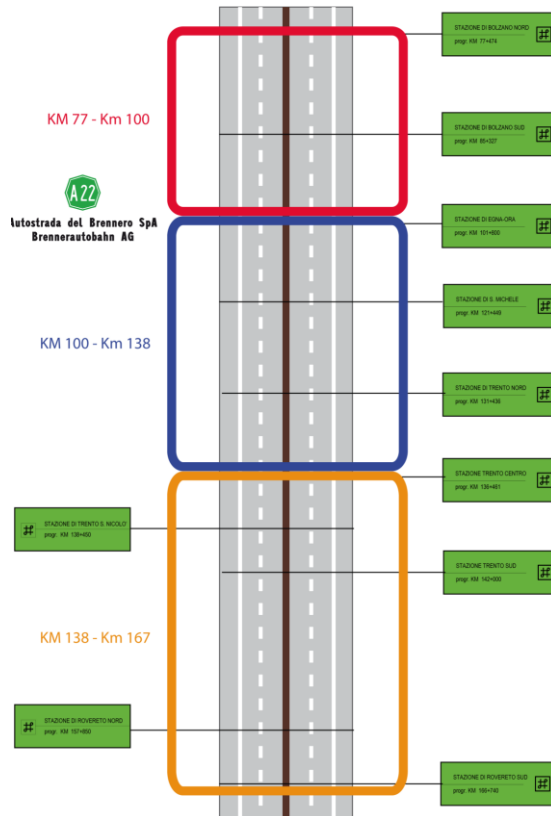
- State change as a function of:

- (Equivalent) nr. of vehicles
- Average speed
- Speed variance

evaluated on a lane level.

- Initial **thresholds** to be empirically fine-tuned

Next testing phase



- Test start scheduled in **06/07-2019**
- Only in “**variable speed limit**” mode
- Only in **direction south** (except for central test stretch)
- **Southern test stretch**: VSL to be combined with **hard shoulder running (HSR)**

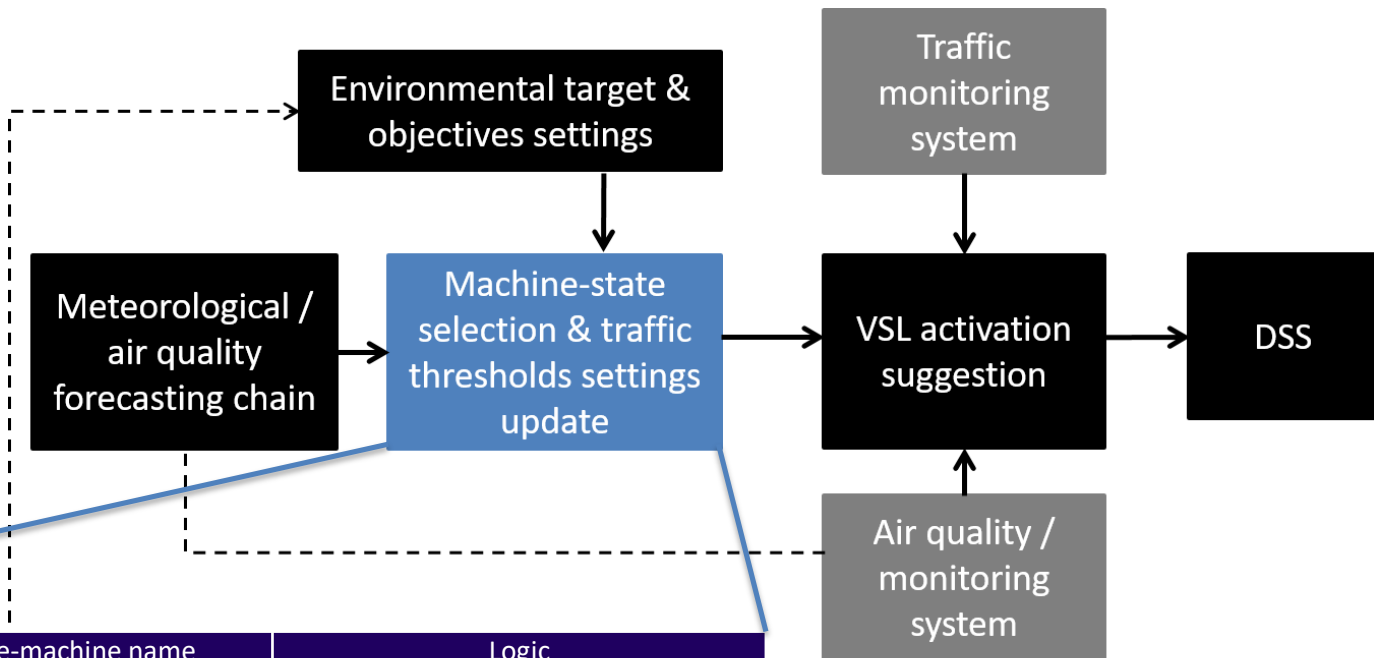


Integrated logic for dynamic VSL activation



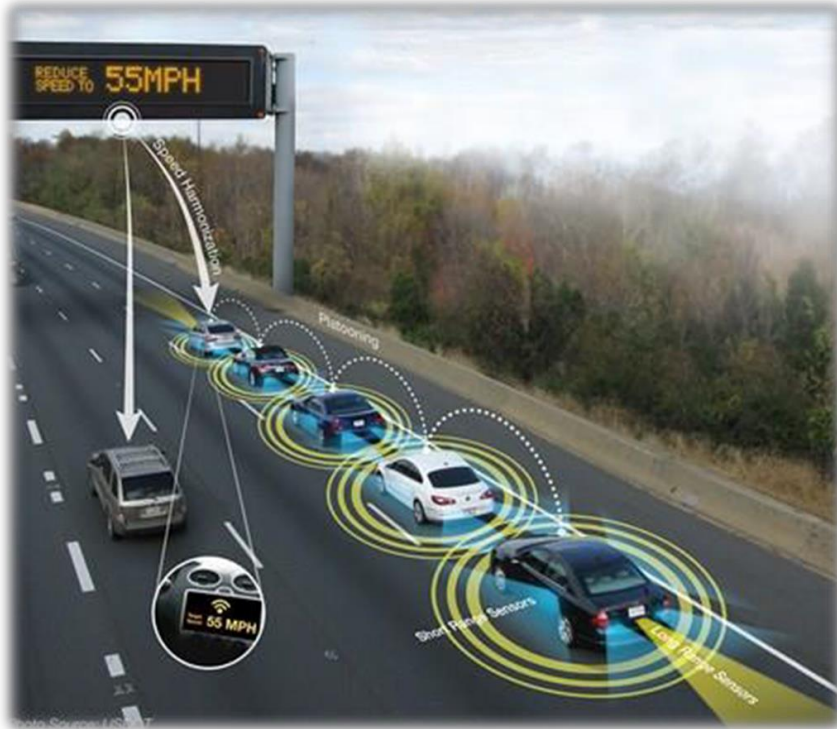
One logic, different thresholds for state change depending on meteorological conditions

Logic to be empirically tested at project in central test stretch, in both direction of travel



Atmospheric stability class	State-machine name	Logic
$\Gamma \geq 5$	"Full-traffic"	130 ↔ 110 ↔ 100 ↔ 90 ↔ 80
$-5 \leq \Gamma < 5$	"Mix traffic / air quality"	130 ↔ 110 ↔ 100 ↔ 90 ↔ 80
$\Gamma < -5$	"Nearly full-air quality"	130 ↔ 110 ↔ 100 ↔ 90 ↔ 80

Preparing for the advent of CAVs



Source: US Department of Transportation



Vision: hybrid C-ITS architecture coupled with novel traffic control measures





Thanks a lot for the attention!

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